

Projects in Wireless Communication Synchronization

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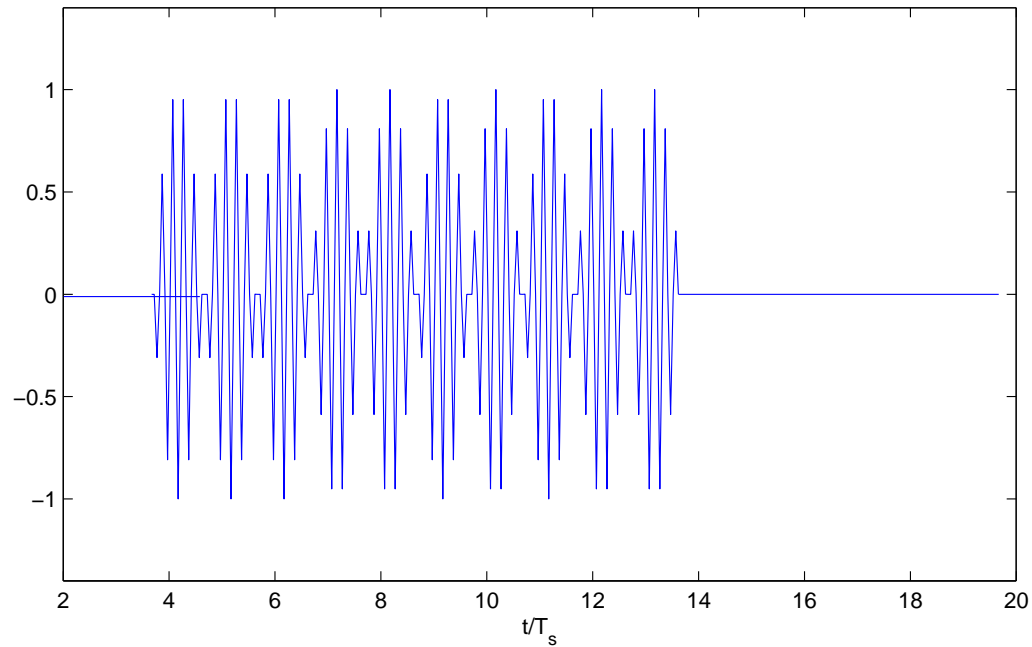
Synchronization

Major problem: We don't know where the signal starts!



Synchronization

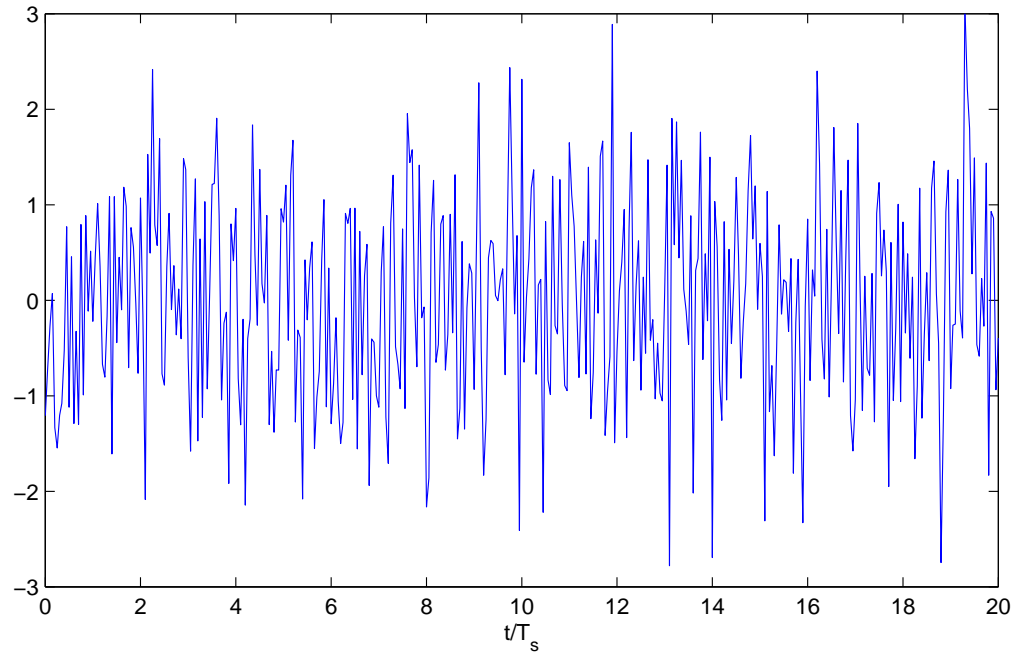
Major problem: **We dont know where the signal starts!**



If there is no noise, its easy....

Synchronization

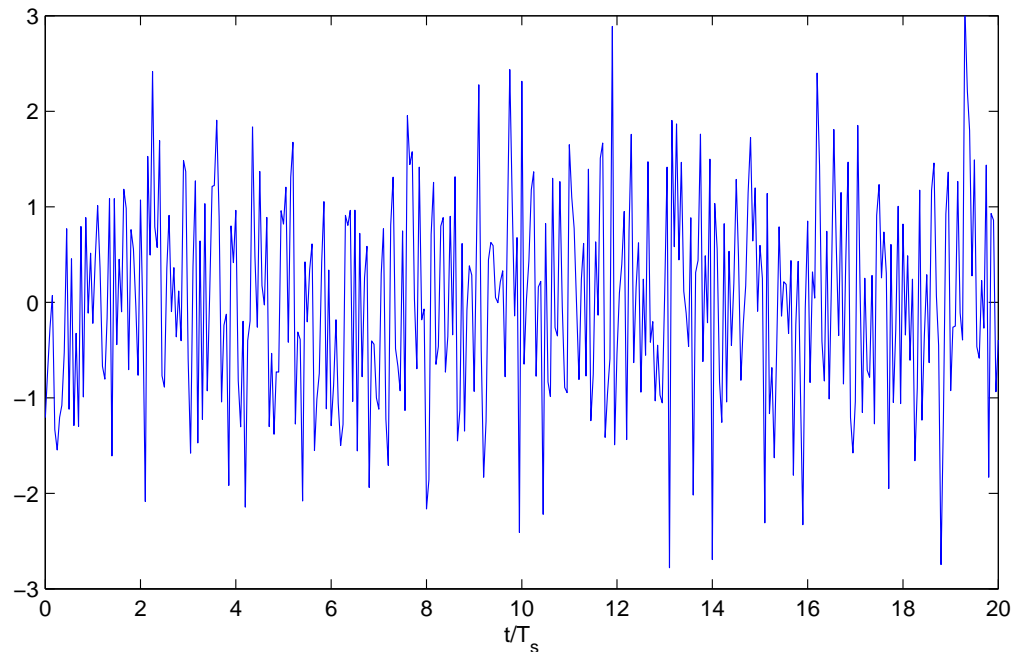
Major problem: **We dont know where the signal starts!**



How about this one?

Synchronization

Major problem: **We don't know where the signal starts!**



How about this one?

The signal starts at $t/T_s = 6.5$ and ends at $t/T_s = 16.5$. $E_b/N_0 = 10$ dB.



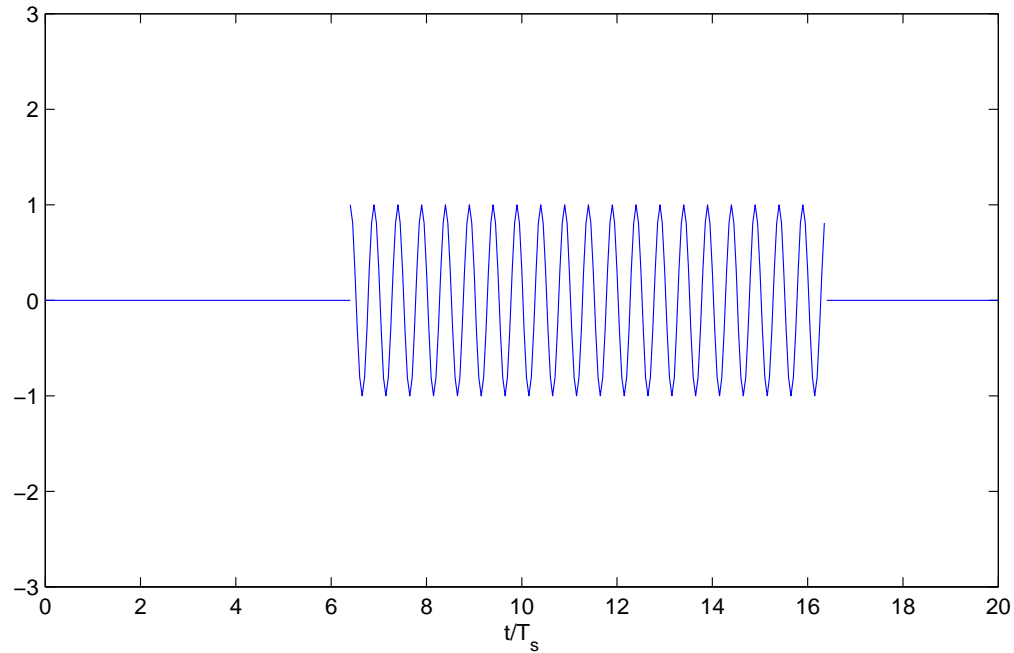
Synchronization

- In general, synchronization is a difficult subject
- Requires solid background in statistical signal processing and control theory
- Phase-locked-loops (PLL) are essential
- We will only make use of simple techniques....



Synchronization

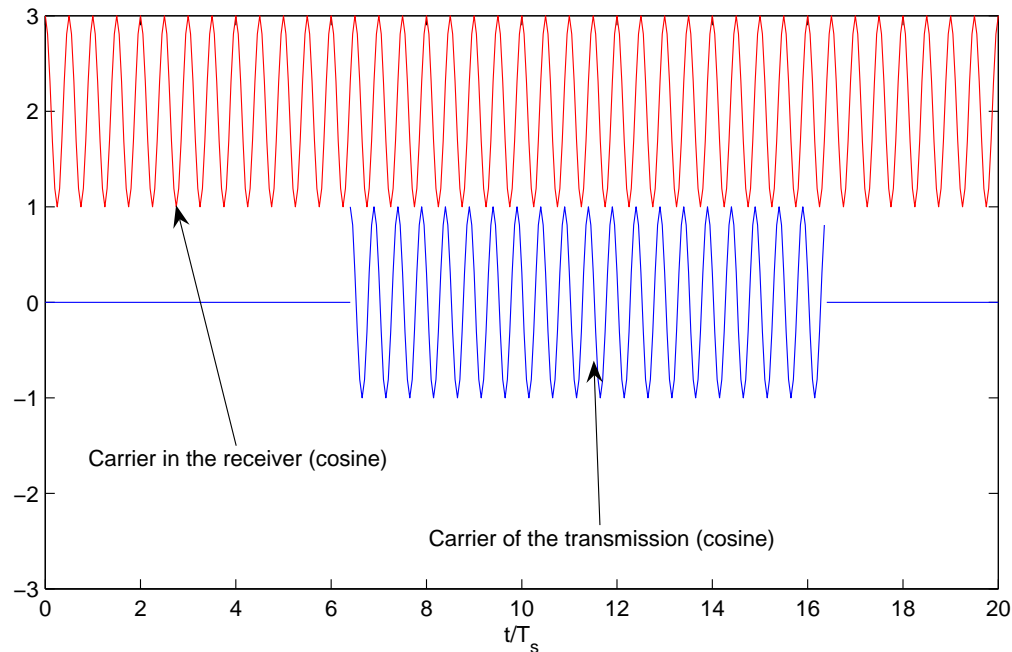
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The transmitted signal (in-phase component) contains a cosine

Synchronization

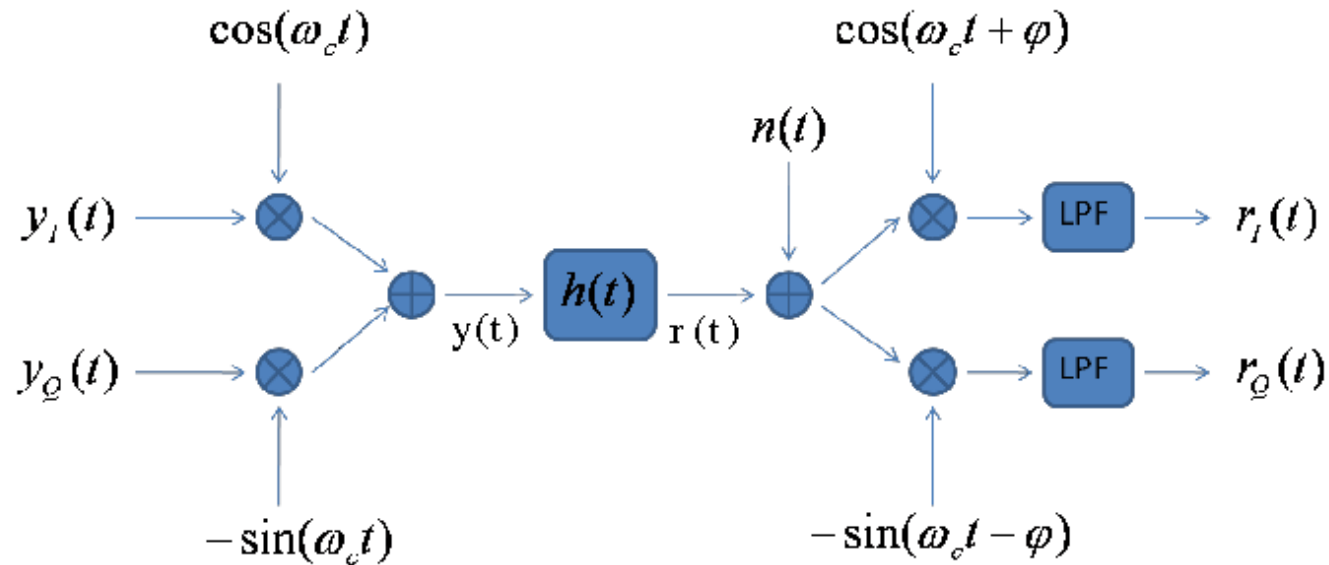
Major problem: **We dont know where the signal starts!**



The transmitted signal (in-phase component) contains a cosine
If we dont know the exact starting position of the signal, the cosine of the reciever and the cosine of the transmission will be **out of phase**

Synchronization

The situation can be represented as below.



Synchronization

Major problem: **We dont know where the signal starts!**

We derived on the last lecture, that if the transmitted complex symbol is a , the the received symbol will be $a \exp(-i\phi)$. Hence, it is crucial that the receiver can estimate ϕ so that it can compensated.



Synchronization

Major problem: **We dont know where the signal starts!**

We derived on the last lecture, that if the transmitted complex symbol is a , the the received symbol will be $a \exp(-i\phi)$. Hence, it is crucial that the receiver can estimate ϕ so that it can compensated.

Moreover, we dont know where the sampling unit (after the matched filter) should sample the signal



Synchronization

We have that the transmitted signal is based on the pulse shape $p(t)$, and the channel is $h(t)$.

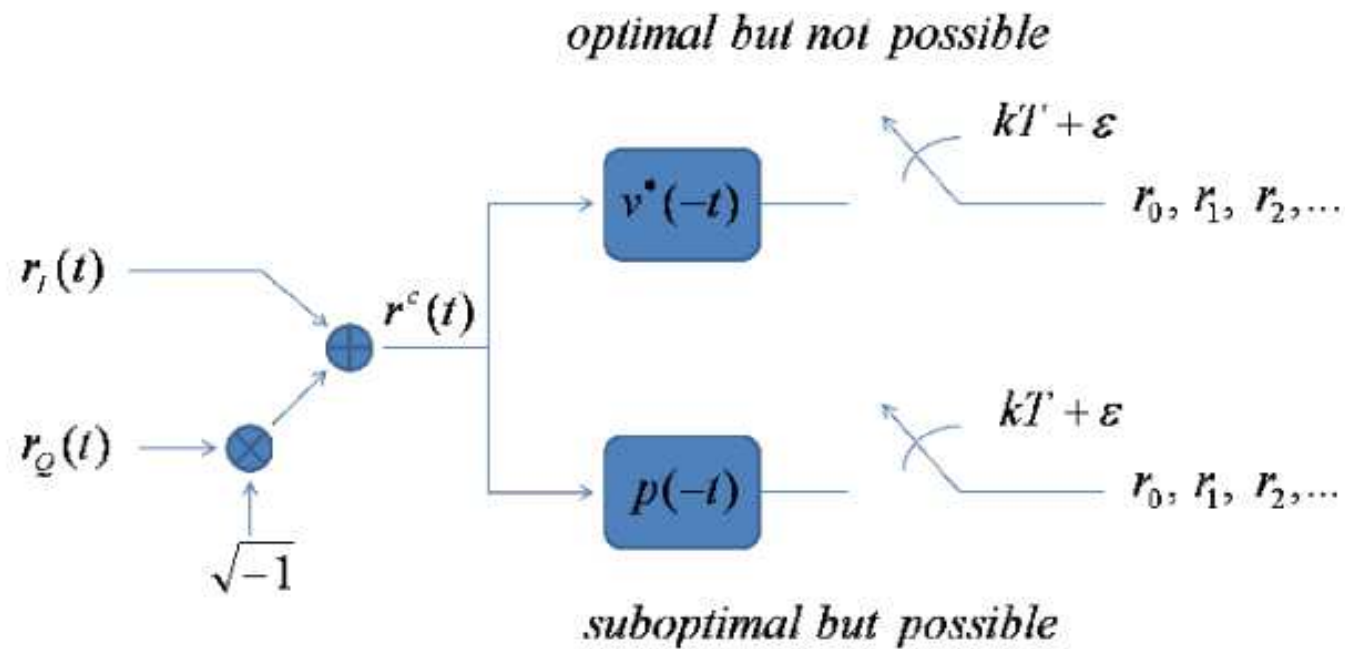
A matched filter should be matched to the receive pulse $v(t) = p(t) \star h(t)$. But, this is not possible in cases where the receiver does not know $h(t)$.

Not knowing ϵ is severe and will be analyzed next.



Synchronization

The situation can be represented as below.



Synchronization

The phase mismatch and non-optimal sampling instance yields a channel model

$$r[k] = \alpha e^{i\phi} a[k] + n[k]$$

Phase mismatch gives ϕ and sampling mismatch gives α

ϕ can be estimated from a pilot symbol p . Let

$$a[1] = p = 1 + i = \sqrt{2}e^{i\pi/4}$$

then

$$\hat{\phi} = \text{angle}\{r[1]\} - \frac{\pi}{4}$$



Synchronization

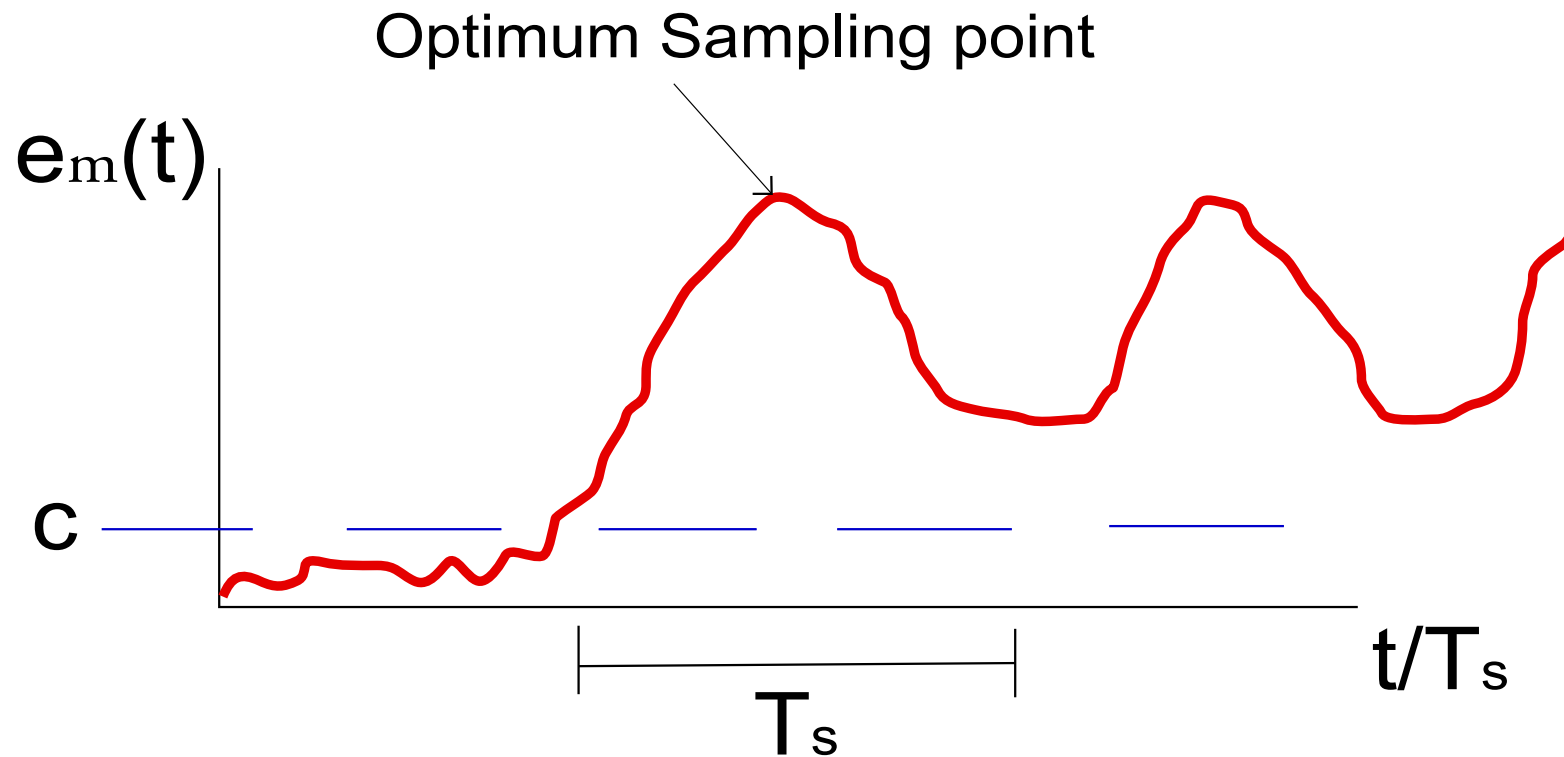
Estimation of ϵ is solved by selecting the sampling instance such that α is maximized.
Recall the receiver structure



Synchronization

$$e_m(t) = \sqrt{m_I^2(t) + m_Q^2(t)}$$

c is a threshold, easiest to find by trial and error



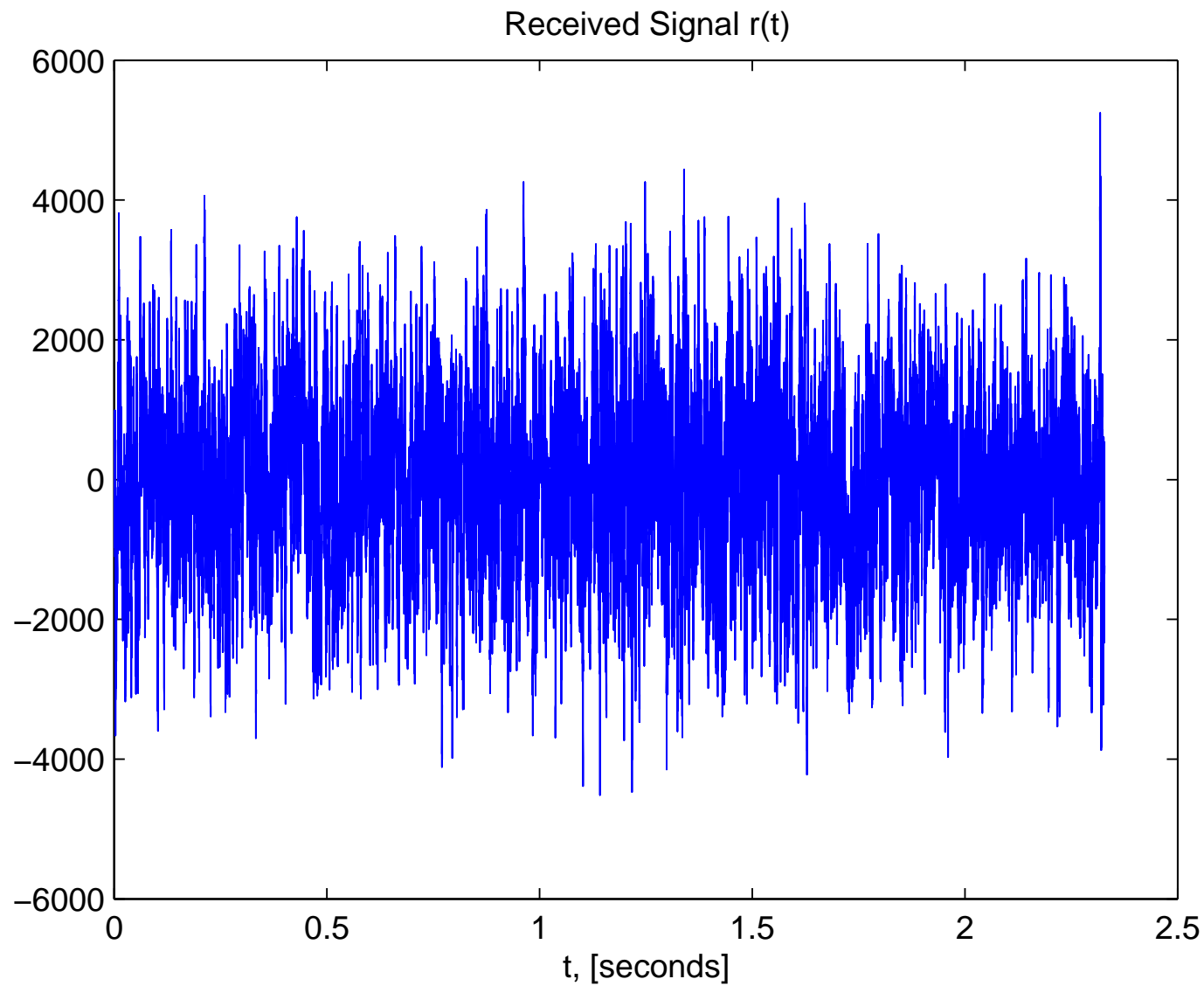
Example

Example

The transmission starts and ends with pilots $2 + 2i$



Example



Example

Construct $m_I(t)$ and $m_Q(t)$ as

$$m_I(t) = r(t) \cos(2\pi f_c t) \star p(t)$$

and

$$m_Q(t) = -r(t) \sin(2\pi f_c t) \star p(t)$$

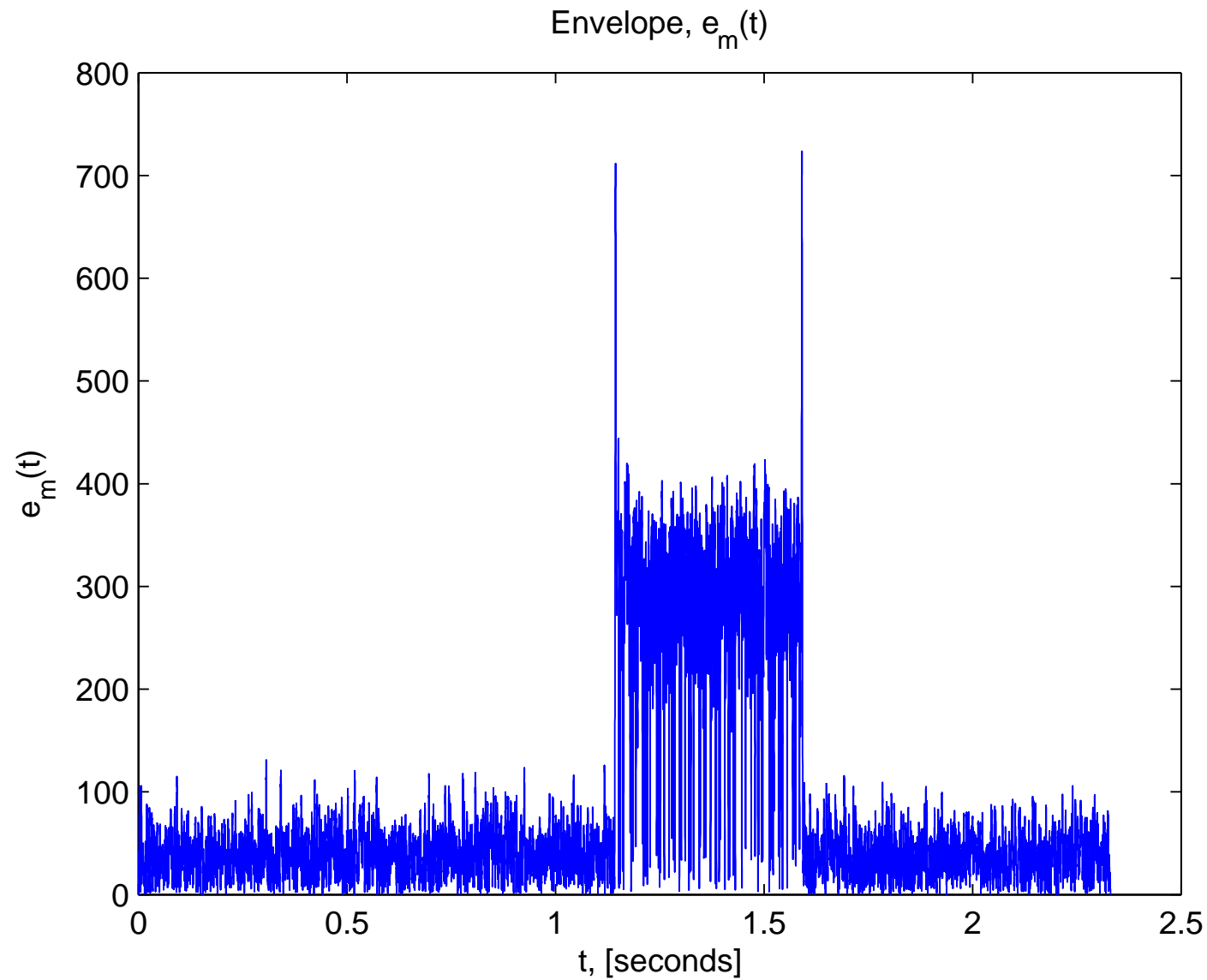
Then generate

$$e_m(t) = \sqrt{m_I^2(t) + m_Q^2(t)}$$

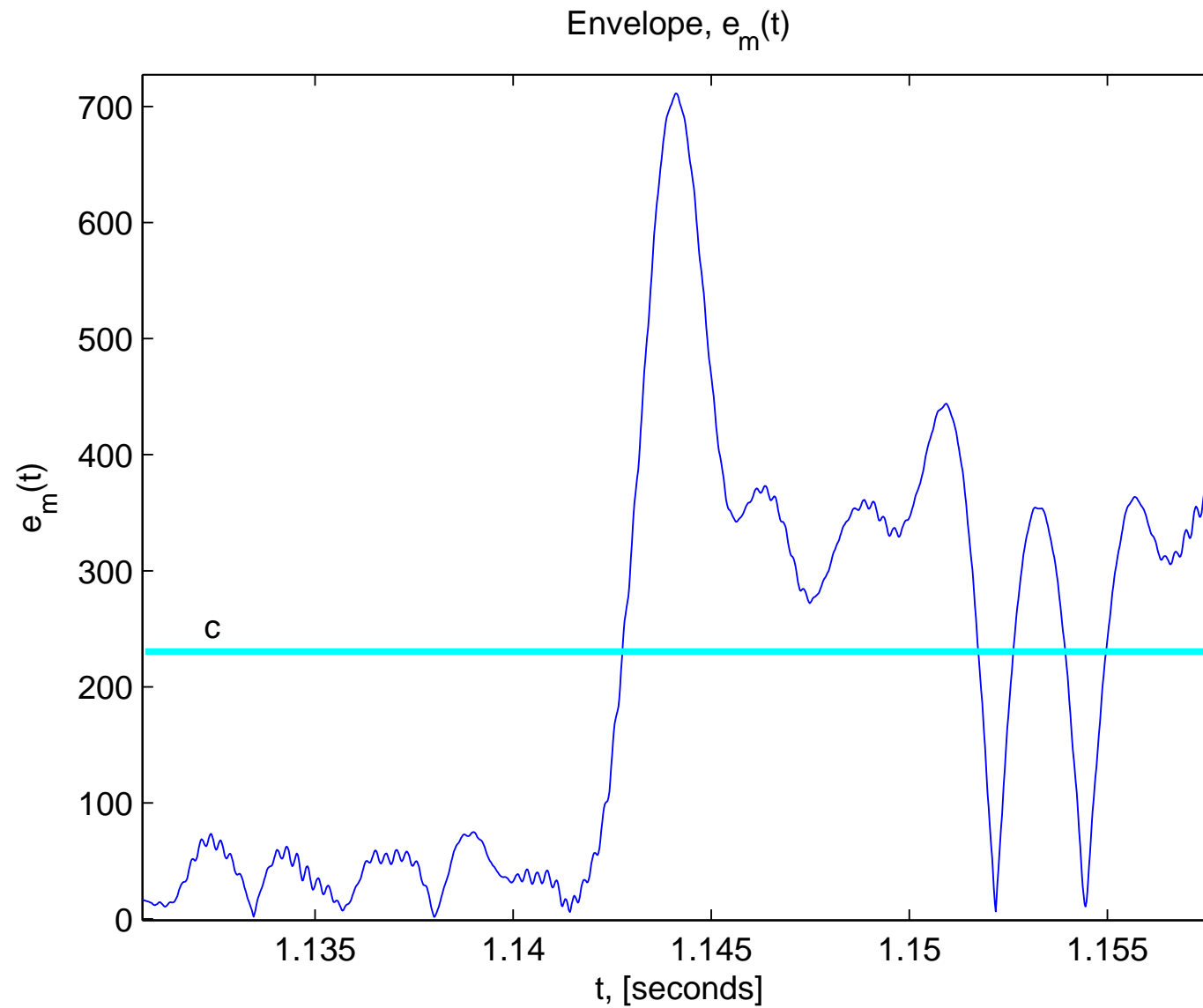
Plot



Example



Example

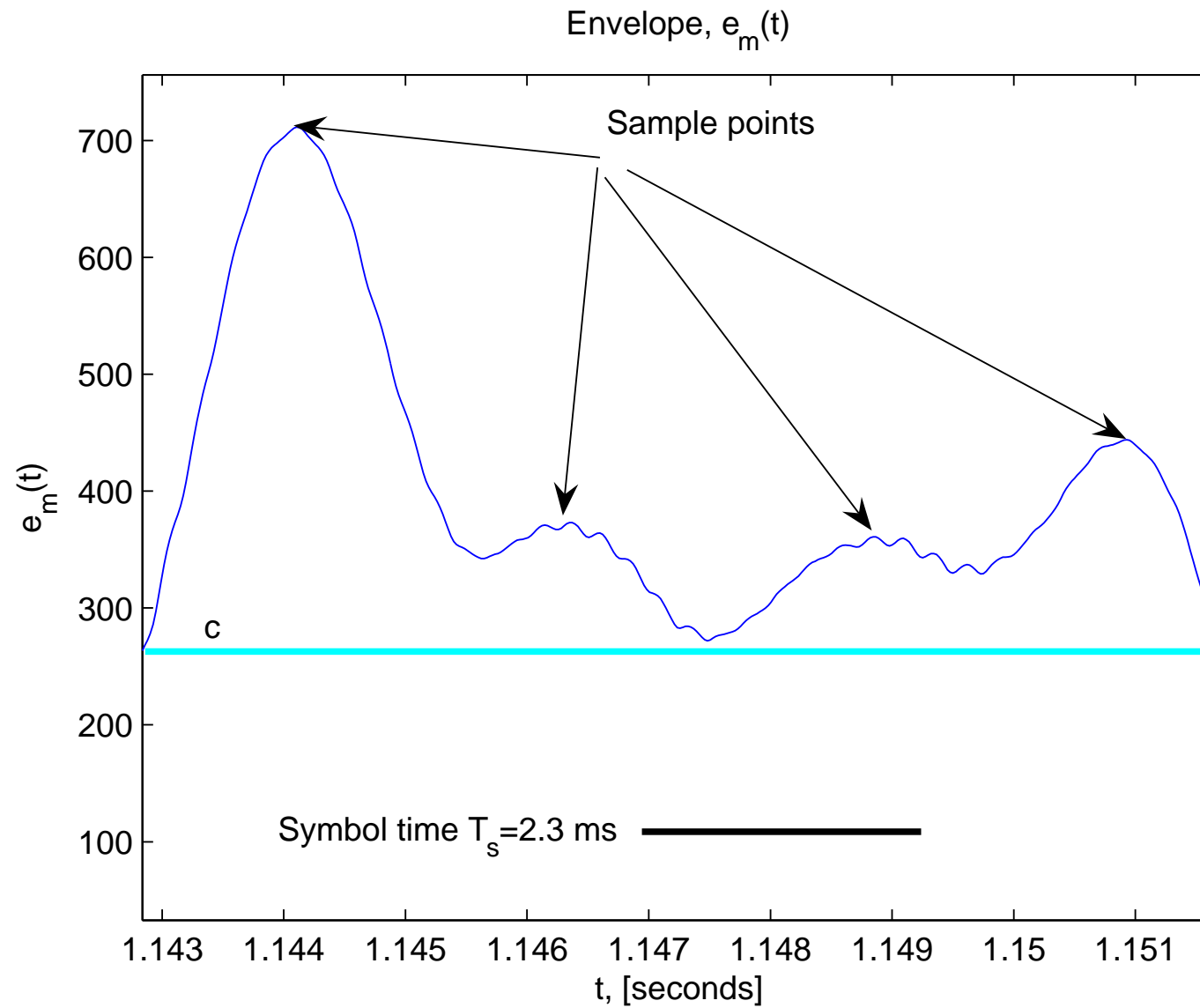


Example

Optimal sampling point is at $T_{\text{Sample}} = 1.144$ seconds.



Example



Example

Sample at $T_{\text{Sample}} + kT_s$:

$$r[k] = m_I(T_{\text{Sample}} + kT_s) + im_Q(T_{\text{Sample}} + kT_s)$$

We get

$$r[k] = 4.38 - 5.60i \quad 3.16 + 1.97i \quad 2.79 + 2.16i \quad 3.55 + 2.66i \quad -2.73 - 2.25i \dots$$

Consequently

$$\alpha \exp(i\phi) = r[0]/(2 + 2i) = -0.30 - 2.49i$$

$$r[1]/\alpha \exp(i\phi) = -0.93 + 1.15i \quad \text{and} \quad r[2]/\alpha \exp(i\phi) = -0.9899 + 0.9982i$$

So

$$\hat{a}[1] = -1 + i \quad \text{and} \quad \hat{a}[2] = -1 + i$$

