

# **Convex Optimization for Optimal Design and Analysis of Small Antennas**

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# Outline

# Acknowledgments

### 2 Motivation

B Physical bounds and background

Antennas and convex optimization Antenna and/or current optimization Stored EM energy Convex optimization Maximal D/Q and G/Q Embedded antennas Why convex optimization

### **5** Summary

# Acknowledgments

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# Collaboration with:

- Doruk Tayli, Lund University
- Marius Cismasu, Ericsson (was LU)
- Sven Nordebo, Linnæus University
- Lars Jonsson, KTH







# Lund University



- Lund university was founded in 1666.
- Sweden's largest university.
- Approximately 40 000 students.
- Department of Electrical and Information Technology: Broadband Communications, Circuits and Systems, Communication, Electromagnetic theory, Networking and Security, Signal Processing.

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# Frame integrated antennas (Sony Xperia)



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Q-factor

The Q-factor is defined as the ratio between the stored electric,  $W_{\rm e}$ , and magnetic,  $W_{\rm m}$ , energies and the dissipated power, *i.e.*,

$$Q = \frac{2\omega \max\{W_{\rm e}, W_{\rm m}\}}{P_{\rm rad} + P_{\rm loss}}.$$

Fractional bandwidth for single resonances (RLC circuits)

$$B \approx \frac{2}{Q} \frac{\Gamma_0}{\sqrt{1 - \Gamma_0^2}}$$



# Physical bounds on antennas

- Tradeoff between performance and size.
- ▶ Performance, e.g., in Q, (half-power fractional bandwidth B ≈ 2/Q), directivity bandwidth product: D/Q, efficiency, capacity,....
- Properties of the best antenna confined to a given (arbitrary) geometry, *e.g.*, spheroid, cylinder, and rectangle.

Physical bounds based on:

- Circuit models.
- Mode expansion (spheres).
- Forward scattering (arbitrary shape).
- Energy expressions in currents.

# $\boldsymbol{k}$

#### Gustafsson, Tayli, and Cismasu 2016

# Physical bounds on antennas: methods



Uses circuit models for the antennas. Used originally by Wheeler (1947), Chu (1948) and later Thal (2006,2013) +simple models +physical intuition ± combined with mode expansions +combined with matching -approximate



on





$$\begin{split} Q &\geq Q_{\rm Chu} = \frac{1}{(ka)^3} + \frac{1}{ka} \qquad \mbox{Chu (1948)} \\ Q &\geq Q_{\rm TE+TM} = \frac{1}{2(ka)^3} + \frac{1}{ka} \qquad \mbox{Chu, McLean (1994), ...} \\ Q &\geq Q_{\rm Thal} = \frac{1.5}{(ka)^3}, ka \ll 1 \quad \mbox{Thal (2006),...} \end{split}$$



Uses the forward scattering sum rule to analyze receiving antennas, see Gustafsson, Sohl & Kristensson

(2007,2009) 50: +arbitrary shape and size +bandwidth +closed form expressions +based on an identity -entire volumes -absorption efficiency



Arbitrary circumscribing shape with polarizability  $\gamma_{
m e}$ 

### Forward scattering bound (2007)

$$\frac{D}{Q} \leq \frac{\eta k^3}{2\pi} \hat{\boldsymbol{e}} \cdot \boldsymbol{\gamma}_{\rm e} \cdot \hat{\boldsymbol{e}}$$

small electric dipoles (D = 1.5,  $\eta = 0.5$ )

$$Q \ge rac{6\pi}{k^3 \hat{m{e}} \cdot m{\gamma}_{
m e} \cdot \hat{m{e}}} \ge Q_{
m Thal} = rac{1.5}{(ka)^3}$$

$${m \gamma}_{
m e}$$
 polarizability dyadic.











# Physical bounds on antennas: methods



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# Antenna and antenna current optimization

Antenna design: produce the desired current distribution on the structure by shaping and choosing the materials.

Have a given maximal size for the antenna structure.

- Antenna optimization: determine the shape and material properties for optimal performance.
- Antenna current optimization: determine an optimal current distribution from all possible currents in the available geometry.

# Maximal size of the antenna $\oint_{U_{y}} \qquad \begin{array}{c} \Omega \\ \ell_{y} \\ \ell_{x} \end{array} = \Omega_{A}$



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# Optimization of antenna currents: examples

### Gain over Q

 $\begin{array}{ll} \mbox{minimize} & \mbox{Stored energy} \\ \mbox{subject to} & \mbox{Radiation intensity} = P_0 \end{array}$ 

### **Q** for superdirectivity $D \ge D_0$ .

minimize Stored energy

subject to Radiation intensity  $= D_0 P_{\rm rad}/(4\pi)$ Radiated power  $< P_{\rm rad}$ 

### **Embedded structures**

minimize Stored energy

subject to Radiation intensity =  $P_0$ 

Correct induced currents

### Need to:

- 1. Express the stored energy in the current density J.
- 2. Solve the optimization problems.



# Stored electromagnetic energy

- Where is the energy stored?
  - Fields
  - Currents
  - Feed structure
- Stored according to what?
  - Input impedance
  - Material
  - Scatterer
- Why are we interested?
  - Basics physics
  - Antenna bandwidth
  - Physical bounds



There are several proposals for the stored energy in the literature. They agree for many cases but differ for some. Differences often due to different interpretations, assumptions, and applications.
# Stored electromagnetic energy

- Where is the energy stored?
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RCL  $Q_{Z'}$ 

Subtract the 'radiated' energy density

- Power flow [1]
- ▶ Far field [2,3], ...
- Differ for standing waves
- Spherical modes
- Can be coordinate dependent [3]
- Inhomogeneous and lossy media?

 $Q_{\mathbf{Z}'}$ 

- ▶ *F* = 0 for a lossy background
- 1. Collin and Rothschild 1964
- 2. Fante 1969
- 3. Yaghjian and Best 2005









 $\boldsymbol{Q}$  from the input impedance:

- Synthesize a lumped circuit model [1,2]
- Stored energy in inductors and capacitors
- Differentiate the reactance matrix X' [3]
- $Q_{\mathrm{Z}'}$  from the input impedance:
  - Differentiate  $Z_{in}$  to get  $Q_{Z'} = \frac{\omega |Z'_{in}|}{2R_{in}}$  [4]
  - $Q \to Q_{\mathrm{Z}'}$  by  $\mathbf{I}^{\mathsf{H}} \to \mathbf{I}^{\mathrm{T}}$  and  $Q_{\mathrm{Z}'} \leq Q$
  - $Q_{\mathbf{Z}'} \approx 0$  for multiple resonance cases [5,6]

1. Brune 1931

- 2. Gustafsson and Jonsson 2015a
- 3. Gustafsson, Tayli, and Cismasu 2014
- 4. Yaghjian and Best 2005
- 5. Gustafsson and Nordebo 2006
- 6. Stuart, Best, and Yaghjian 2007



 $\begin{aligned} & \mathsf{Kirchhoff} \\ & \mathbf{ZI} = \mathbf{V} \\ & \frac{1}{4} \mathbf{I}^{\mathsf{H}} \mathbf{X}' \mathbf{I} \end{aligned}$ 

 $Z_{\rm in}I_{\rm in} = V_{\rm in}$ 

 $|Z'_{\rm in}| = \frac{|\mathbf{I}^{\rm T}\mathbf{X}'\mathbf{I}|}{|\mathbf{I}_{\rm T}|^2}$ 

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 $Q_{\mathbf{Z}'}$ 





Stored energy expressed in the current density [1-5]

- MoM implementation of the EFIE [3]
- Quadratic form in the current (antenna current optimization)
- ► Can be negative [4]
- ► Q<sub>Z'</sub> expressed in the current [5,6]

 $|Z'_{\rm in}| = \frac{|\mathbf{I}^{\rm T}\mathbf{X}'\mathbf{I}|}{|\mathbf{I}_{\rm r}|^2}$ 

- 1. Vandenbosch 2010
- 2. Geyi 2003b

 $\frac{1}{4} |\mathbf{I}^{\mathrm{T}} \mathbf{Z}' \mathbf{I}|$ 

- 3. Harrington and Mautz 1972
- 4. Gustafsson, Cismasu, and Jonsson 2012
- 5. Capek et al. 2014
- 6. Gustafsson, Tayli, and Cismasu 2014

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 $\frac{1}{4}\mathbf{I}^{\mathsf{H}}\mathbf{X}'\mathbf{I}$ 

MoM

 $\mathbf{ZI} = \mathbf{V}$ 









Use a method of moments (MoM) formulation of the electric field integral equation (EFIE). Impedance matrix  ${\bf Z}={\bf R}+j{\bf X}$ 

$$\frac{Z_{mn}}{\eta} = j \int_{\Omega} \int_{\Omega} \left( k \boldsymbol{\psi}_{m1} \cdot \boldsymbol{\psi}_{n2} - \frac{1}{k} \nabla_1 \cdot \boldsymbol{\psi}_{m1} \nabla_2 \cdot \boldsymbol{\psi}_{n2} \right) \frac{\mathrm{e}^{-\mathrm{j}kr_{12}}}{4\pi r_{12}} \,\mathrm{dS}_1 \,\mathrm{dS}_2$$

where  $\psi_{n1} = \psi_n(\mathbf{r}_1)$ ,  $\psi_{n2} = \psi_n(\mathbf{r}_2)$ , m, n = 1, ..., N, and  $r_{12} = |\mathbf{r}_1 - \mathbf{r}_2|$ . The current density is  $\mathbf{J}(\mathbf{r}) = \sum_{n=1}^N I_n \psi_n(\mathbf{r})$  with the expansion coefficients determined from  $\mathbf{ZI} = \mathbf{V}$ , where  $\mathbf{V}$  is a column matrix with the excitation coefficients.

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$$\frac{k \partial Z_{mn}}{\eta \partial k} = \int_{\Omega} \int_{\Omega} j \left( k \boldsymbol{\psi}_{m1} \cdot \boldsymbol{\psi}_{n2} + \frac{1}{k} \nabla_1 \cdot \boldsymbol{\psi}_{m1} \nabla_2 \cdot \boldsymbol{\psi}_{n2} \right) \frac{\mathrm{e}^{-jkr_{12}}}{4\pi r_{12}} \\ + k \left( k \boldsymbol{\psi}_{m1} \cdot \boldsymbol{\psi}_{n2} - \frac{1}{k} \nabla_1 \cdot \boldsymbol{\psi}_{m1} \nabla_2 \cdot \boldsymbol{\psi}_{n2} \right) \frac{\mathrm{e}^{-jkr_{12}}}{4\pi} \, \mathrm{dS}_1 \, \mathrm{dS}_2$$

Use a method of moments (MoM) formulation of the electric field integral equation (EFIE). Impedance matrix  ${\bf Z}={\bf R}+j{\bf X}$ 

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where  $\psi_{n1} = \psi_n(\mathbf{r}_1)$ ,  $\psi_{n2} = \psi_n(\mathbf{r}_2)$ , m, n = 1, ..., N, and  $r_{12} = |\mathbf{r}_1 - \mathbf{r}_2|$ . The current density is  $\mathbf{J}(\mathbf{r}) = \sum_{n=1}^N I_n \psi_n(\mathbf{r})$ with the expansion coefficients determined from  $\mathbf{ZI} = \mathbf{V}$ , where  $\mathbf{V}$ is a column matrix with the excitation coefficients. Differentiate the MoM impedance matrix

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Use a method of moments (MoM) formulation of the electric field integral equation (EFIE). Impedance matrix  ${\bf Z}={\bf R}+j{\bf X}$ 

$$\begin{split} & \frac{Z_{mn}}{\eta} = j \int_{\Omega} \int_{\Omega} \left( k \psi_{m1}^{W} \cdot \psi_{n2} - \frac{1}{k} \nabla_1 \cdot \psi_{m1} \nabla_2 \cdot \psi_{n2} \right) \frac{e^{-jkr_{12}}}{4\pi r_{12}} \, dS_1 \, dS_2 \\ & \text{where } \psi_{n1} = \psi_n(\boldsymbol{r}_1), \ \psi_{n2} = \psi_n(\boldsymbol{r}_2), \ m, n = 1, \dots, N, \text{ and} \\ & r_{12} = |\boldsymbol{r}_1 - \boldsymbol{r}_2|. \text{ The current density is } \boldsymbol{J}(\boldsymbol{r}) = \sum_{n=1}^N I_n \psi_n(\boldsymbol{r}) \\ & \text{with the expansion coefficients determined from } \mathbf{ZI} = \mathbf{V}, \text{ where } \mathbf{V} \\ & \text{is a column matrix with the excitation coefficients.} \end{split}$$

Differentiate the MoM impedance matrix

$$\frac{k \partial Z_{mn}}{\eta \partial k} = \int_{\Omega} \int_{\Omega} j \left( k \psi_{m1} \cdot \psi_{n2} + \frac{1}{k} \nabla_1 \cdot \psi_{m1} \nabla_2 \cdot \psi_{n2} \right) \frac{e^{-jkr_{12}}}{4\pi r_{12}} + k \left( k \psi_{m1} \cdot \psi_{n2} - \frac{1}{k} \nabla_1 \cdot \psi_{m1} \nabla_2 \cdot \psi_{n2} \right) \frac{e^{-jkr_{12}}}{4\pi} dS_1 dS_2$$

Standard MoM implementations of the EFIE are easily modified to compute the stored energies. The sum and differences

$$W_{\mathrm{m}} + W_{\mathrm{e}} = \frac{1}{4} \mathbf{I}^{\mathsf{H}} \mathbf{X}' \mathbf{I}$$
 and  $W_{\mathrm{m}} - W_{\mathrm{e}} = \frac{1}{4\omega} \mathbf{I}^{\mathsf{H}} \mathbf{X} \mathbf{I}$ 

gives the stored magnetic and electric energies

$$W_{\rm m} = \frac{1}{8} \mathbf{I}^{\sf H} \left( \frac{\partial \mathbf{X}}{\partial \omega} + \frac{\mathbf{X}}{\omega} \right) \mathbf{I} \quad \text{and} \ W_{\rm e} = \frac{1}{8} \mathbf{I}^{\sf H} \left( \frac{\partial \mathbf{X}}{\partial \omega} - \frac{\mathbf{X}}{\omega} \right) \mathbf{I},$$

respectively. Electric  $\mathbf{X}_{e}\text{,}$  and magnetic  $\mathbf{X}_{m}\text{,}$  reactance matrices

$$\mathbf{X}_{\mathrm{e}} = rac{1}{2} \left( \omega \mathbf{X}' - \mathbf{X} 
ight) \quad ext{and} \ \mathbf{X}_{\mathrm{m}} = rac{1}{2} \left( \omega \mathbf{X}' + \mathbf{X} 
ight)$$

Identical to the stored energy expression (free space) introduced by Vandenbosch 2010, see • 69 and already considered by Harrington and Mautz 1972.

### Matrix expressions for the stored EM energies

Method of Moments approximation (expand J in basis functions)

$$W_{e} \approx \frac{1}{4\omega} \mathbf{I}^{\mathsf{H}} \mathbf{X}_{e} \mathbf{I}$$
 stored E-energy,  $\mathbf{X}_{e}$  electric reactance  
 $W_{m} \approx \frac{1}{4\omega} \mathbf{I}^{\mathsf{H}} \mathbf{X}_{m} \mathbf{I}$  stored M-energy,  $\mathbf{X}_{m}$  magnetic reactance  
 $P_{rad} \approx \frac{1}{2} \mathbf{I}^{\mathsf{H}} \mathbf{R} \mathbf{I}$  radiated power

giving  $\mathbf{Z} = \mathbf{R} + j(\mathbf{X}_m - \mathbf{X}_e).$  We also use

$$\hat{m{e}}^*\cdotm{F}pprox {f FI}$$
 far field  
 $m{E}pprox {f NI}$  near field  
 $f I_{
m G}pprox {f CI}_{
m A}$  induced current on a PEC

## Matrix expressions for the stored EM energies

Method of Moments approximation (expand J in basis functions)

$$W_{\rm e} \approx \frac{1}{4\omega} \mathbf{I}^{\mathsf{H}} \mathbf{X}_{\rm e} \mathbf{I}$$
 stored E-energy,  $\mathbf{X}_{\rm e}$  electric reactance  
 $W_{\rm m} \approx \frac{1}{4\omega} \mathbf{I}^{\mathsf{H}} \mathbf{X}_{\rm m} \mathbf{I}$  stored M-energy,  $\mathbf{X}_{\rm m}$  magnetic reactance  
 $P_{\rm rad} \approx \frac{1}{2} \mathbf{I}^{\mathsf{H}} \mathbf{R} \mathbf{I}$  radiated power

giving  $\mathbf{Z} = \mathbf{R} + j(\mathbf{X}_m - \mathbf{X}_e).$  We also use

$$\hat{e}^* \cdot F \approx FI$$
 far field  
 $E \approx NI$  near field  
 $I_G \approx CI_A$  induced current on a PEC

#### Pre-computed matrices used in the optimization.

# Optimization of the current distribution

Characteristic modes Modes with small Rayleigh quotients

$$\frac{\mathbf{I}^{\mathsf{H}}\mathbf{X}\mathbf{I}}{\mathbf{I}^{\mathsf{H}}\mathbf{R}\mathbf{I}} = \frac{\mathbf{I}^{\mathsf{H}}(\mathbf{X}_{\mathrm{m}} - \mathbf{X}_{\mathrm{e}})\mathbf{I}}{\mathbf{I}^{\mathsf{H}}\mathbf{R}\mathbf{I}}$$

Eigenvalue problem

 $(\mathbf{X}_{m} - \mathbf{X}_{e})\mathbf{I} = \nu \mathbf{R}\mathbf{I}$ 

- Modes with low reactive power.
- Resonances ( $\nu = 0$ )
- Does not enforce

low stored energy.

#### Stored energy

Minimize the energy Rayleigh quotient

$$\frac{\mathbf{I}^{\mathsf{H}}(\mathbf{X}_{\mathrm{m}}+\mathbf{X}_{\mathrm{e}})\mathbf{I}}{\mathbf{I}^{\mathsf{H}}\mathbf{R}\mathbf{I}}$$

Eigenvalue problem

$$(\mathbf{X}_{\rm m} + \mathbf{X}_{\rm e})\mathbf{I} = \nu \mathbf{R}\mathbf{I}$$

- Modes with low stored energy.
- Does not enforce

resonance.

#### **Q**-factor

Minimize the Q-factor quotient

### $2 \max \{ \mathbf{I}^{\mathsf{H}} \mathbf{X}_{\mathsf{m}} \mathbf{I}, \mathbf{I}^{\mathsf{H}} \mathbf{X}_{\mathsf{e}} \mathbf{I} \}$ THBI

- Currents with low Q-factors.
- Resonance by tuning.
- Need to solve these optimization problems  $\Rightarrow$  convex
- optimization.

Chen and Wang 2015; Garbacz and Turpin 1971; Harrington and Mautz 1971, see also 277



### Convex optimization

minimize  $f_0(\mathbf{x})$ subject to  $f_i(\mathbf{x}) \le 0, \ i = 1, ..., N_1$  $\mathbf{A}\mathbf{x} = \mathbf{b}$ 



where  $f_i(x)$  are convex, *i.e.*,  $f_i(\alpha \mathbf{x} + \beta \mathbf{y}) \leq \alpha f_i(\mathbf{x}) + \beta f_i(\mathbf{y})$  for  $\alpha, \beta \in \mathbb{R}, \ \alpha + \beta = 1, \ \alpha, \beta \geq 0.$ 

Solved with efficient standard algorithms. No risk of getting trapped in a local minimum. A problem is 'solved' if formulated as a convex optimization problem.

Antenna performance expressed in the current density J, e.g.,

- ► Radiated field  $F(\hat{k}) = -\hat{k} \times \hat{k} \times \int_{\Omega} J(r) e^{jk\hat{k} \cdot r} dV$  is affine.
- Radiated power, stored electric and magnetic energies, and Ohmic losses are positive semi-definite quadratic forms in J.

### Convex optimization for antennas

Convex optimization offer many possibilities to analyze radiating structures. Common convex quantities:

linear forms near fields  $N_{\rm e}I$  and  $N_{\rm m}I$ , far field FI, and induced currents CI.

 $\begin{array}{l} \mbox{quadratic forms radiated power } \mathbf{I}^{H}\mathbf{R}\mathbf{I}, \mbox{ absorbed power, stored} \\ \mbox{ electric energy } \mathbf{I}^{H}\mathbf{X}_{e}\mathbf{I}, \mbox{ stored magnetic energy } \mathbf{I}^{H}\mathbf{X}_{m}\mathbf{I}, \\ \mbox{ ohmic losses } \mathbf{I}^{H}\mathbf{R}_{\Omega}\mathbf{I}. \end{array}$ 

norms field strengths  $||\mathbf{NI}||$ , far-field levels  $||\mathbf{FI}||$ 

max stored energy for tuned antennas  $W = \max\{W_e, W_m\}$ logarithmic capacity (can be).

in the current density. In convex optimization, we can

- minimize convex quantities.
- maximize concave quantities.

The linear (affine) quantities are both convex and concave. Quadratic positive semidefinite forms are convex.

# Currents for maximal ${\cal G}/Q$

Determine a current density J(r) in the volume V that maximizes the partial-gain Q-factor quotient  $G(\hat{k}, \hat{e})/Q$ .

Partial radiation intensity P( \u03c6 k, \u03c6 )

$$\frac{G(\hat{\boldsymbol{k}}, \hat{\boldsymbol{e}})}{Q} = \frac{2\pi P(\hat{\boldsymbol{k}}, \hat{\boldsymbol{e}})}{c_0 k \max\{W_{\rm e}, W_{\rm m}\}}.$$

- Scale J and reformulate max.P as max. Re{ê<sup>\*</sup> ⋅ F}.
  - Convex optimization problem. maximize  $\operatorname{Re}\{\mathbf{FI}\}$ subject to  $\mathbf{I}^{\mathsf{H}}\mathbf{X}_{e}\mathbf{I} \leq 1$  $\mathbf{I}^{\mathsf{H}}\mathbf{X}_{m}\mathbf{I} \leq 1$



Determines a current density  ${\bm J}({\bm r})$  in the volume V with maximal partial radiation intensity and unit stored EM energy.

# Maximal $G(\hat{m{k}}, \hat{m{x}})/Q$ for planar rectangles

Solution of the convex optimization problem

$$\label{eq:rescaled_response} \begin{split} \max & \operatorname{Re}\{\mathbf{F}\mathbf{I}\} \\ \text{s.t.} & \mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{e}}\mathbf{I} \leq 1 \\ & \mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{m}}\mathbf{I} \leq 1 \end{split}$$

or

for current densities confined to planar rectangles with side lengths  $\ell_x$  and  $\ell_y=\{0.01,0.1,0.2,0.5\}\ell_x.$ 

Note 
$$\ell_{\rm x}/\lambda = k\ell_{\rm x}/(2\pi)$$
, giving  $\ell_{\rm x} = \lambda/2 \rightarrow k\ell_{\rm x} = \pi \rightarrow ka \ge \pi/2$ .



# D/Q (or G/Q) bounds

#### Typical (but not optimal) MATLAB code using CVX

```
cvx_begin
variable I(n) complex; % current density
maximize(real(F*I)) % far-field
subject to
quad_form(I,Xe) <= 1; % stored E energy
quad_form(I,Xm) <= 1; % stored M energy
cvx_end
```

- ▶ Similar to the forward scattering bounds (2007) for TM.
- Can design 'optimal' electric dipole mode (TM) antennas.
- ► TE modes and TE+TM are not well understood.

We now reformulate the complex optimization problem to analyze superdirectivity, antennas with a prescribed radiation pattern, losses, and antennas embedded in a PEC structure.

# Optimal performance for embedded antennas

- Common with antennas embedded in metallic structures.
- The induced currents radiate but they are not arbitrary.
- Linear map from the antenna region adds a (convex) constraint.
- Here, we assume that the surrounding structure is PEC and add a constraint to account for the induced currents on the surrounding structure in the G/Q formulation.



# Currents for maximal G/Q for embedded antennas

Determine an optimal current density  $J_A(r)$  in the region  $\Omega_A$ . Assume that the ground plane  $\Omega_G = \Omega \setminus \Omega_A$  is PEC.

Can minimize the stored energy for given radiated field

$$\begin{split} & \text{minimize} & \max\{\mathbf{I}^{\mathsf{H}}\mathbf{X}_{e}\mathbf{I},\mathbf{I}^{\mathsf{H}}\mathbf{X}_{m}\mathbf{I}\} \\ & \text{subject to} & \mathbf{F}\mathbf{I}=1 \\ & \mathbf{I}_{G}=\mathbf{C}\mathbf{I}_{A} \end{split}$$

or maximize the radiated field for given stored energy

 $\begin{array}{ll} \mbox{maximize} & {\rm Re}\{{\bf FI}\} \\ \mbox{subject to} & {\bf I}^{\sf H}{\bf X}_{\rm e}{\bf I} \leq 1 \\ & {\bf I}^{\sf H}{\bf X}_{\rm m}{\bf I} \leq 1 \\ & {\bf I}_{\rm G}={\bf CI}_{\rm A} \end{array}$ 



Can also eliminate  $\mathbf{I}_{\mathrm{G}}.$ 

#### Embedded antennas in planar PEC rectangles



# Finite ground plane with $\{6,10,25,100\}\%$ antenna region



# Finite ground plane with $\{6,10,25,100\}\%$ antenna region



# Why convex optimization?

**Solved** if formulated as a convex optimization problem.

Consider the  ${\cal G}/{\cal Q}$  problem

Many (optimization) algorithms can be used to solve this problem.

► Can e.g., use any of the solvers included in CVX.

- Very simple to use.
- Good for small problems but less efficient for larger problems.
- A dedicated solver for quadratic programs.
  - More efficient for larger problems.
- Random search, eg genetic algorithms (GA), particle swarms,....
  - ▶ Very inefficient. Note you do not (should not) use (GA, ...) to solve *e.g.*, Ax = b (min.||Ax b||).
- We also use a dual formulation
  - Computational efficient for large problems.
  - Illustrates dual problems and posteriori error estimates.

#### Why convex optimization: illustration

The upper bound on  $G/Q|_{opt}$  is obtained by solving the dual (relaxed) problem, *i.e.*, finding the minimum of the (red) curve

$$\left. \frac{G}{Q} \right|_{\text{opt}} \leq \frac{G_{\alpha}}{\alpha Q_{\text{e}\alpha} + (1 - \alpha) Q_{\text{m}\alpha}}$$

Efficiently solved with Newton iterations (cost Ax = b per it).



 $\ell/\lambda\approx 0.1~{\rm or}~ka\approx 0.35$ 

#### Why convex optimization: illustration



We also compute the actual G/Q for the (dual) current  $I_{\alpha}$  to get

 $\ell/\lambda\approx 0.1~{\rm or}~ka\approx 0.35$ 

$$\frac{G_{\alpha}}{\max\{Q_{\mathrm{e}\alpha}, Q_{\mathrm{m}\alpha}\}} \le \left. \frac{G}{Q} \right|_{\mathrm{opt}}$$
## Why convex optimization: illustration

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 $\ell/\lambda\approx 0.1~{\rm or}~ka\approx 0.35$ 

The Newton iterations converge as  $\alpha \approx 0.5, 0.73536, 0.67677, 0.66629, 0.66602, 0.66602$  with the duality gap in G/Q approximately  $10^{-\{2,2,3,4,8,16\}}$ .

## Why convex optimization: illustration

The upper bound on  $G/Q|_{opt}$  is obtained by solving the dual (relaxed) problem, *i.e.*, finding the minimum of the (red) curve

$$\left. \frac{G}{Q} \right|_{\text{opt}} \leq \frac{G_{\alpha}}{\alpha Q_{\text{e}\alpha} + (1 - \alpha) Q_{\text{m}\alpha}}$$

Efficiently solved with Newton iterations (cost Ax = b per it).

We also compute the actual G/Q for the (dual) current  $\mathbf{I}_{\alpha}$  to get

$$\frac{G_{\alpha}}{\max\{Q_{\mathrm{e}\alpha}, Q_{\mathrm{m}\alpha}\}} \le \left. \frac{G}{Q} \right|_{\mathrm{opt}}$$







## Why: simple optimization formulations

#### Super directivity:

$$\begin{split} \text{minimize} & \max\{\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{e}}\mathbf{I},\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{m}}\mathbf{I}\}\\ \text{subject to} & \mathbf{F}\mathbf{I}=1\\ & \mathbf{I}^{\mathsf{H}}\mathbf{R}_{\mathrm{r}}\mathbf{I}\leq 4\pi/(\eta_{0}D_{0}) \end{split}$$

#### Prescribed far field:

 $\begin{array}{ll} \text{minimize} & \max\{\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{e}}\mathbf{I},\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{m}}\mathbf{I}\}\\ \text{subject to} & \int_{\Omega}|\boldsymbol{F}(\hat{\boldsymbol{k}})-\boldsymbol{F}_{0}(\hat{\boldsymbol{k}})|^{2}\,\mathrm{d}\Omega_{\hat{\boldsymbol{k}}}<\delta \end{array}$ 

#### **Embedded** antennas:

$$\begin{array}{ll} \mathrm{minimize} & \mathrm{max}\{\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{e}}\mathbf{I},\mathbf{I}^{\mathsf{H}}\mathbf{X}_{\mathrm{m}}\mathbf{I}\}\\ \mathrm{subject \ to} & \mathbf{FI}=1\\ & \mathbf{I}_{\mathrm{G}}=\mathbf{CI}_{\mathrm{A}} \end{array}$$



## Outline

#### Acknowledgments

#### 2 Motivation

Physical bounds and background

Antennas and convex optimization Antenna and/or current optimization Stored EM energy Convex optimization Maximal D/Q and G/Q Embedded antennas Why convex optimization

#### **6** Summary

# Summary

- Physical bounds from spheres (Chu 1948) and arbitrary shapes (Gustafsson *etal* 2007) to embedded antennas...
- Stored energy in the current density.
- Optimization of the antenna structure (global optimization) and the antenna currents (convex optimization).
- Convex optimization for bounds and optimal currents: G/Q, superdirective, embedded, ...
- Closed form solutions for small antennas.
- $\blacktriangleright$  Non-Foster to overcome  $B\sim 1/Q$  ...

Initial results for efficiency, more realistic geometries (phones), SAR, MIMO. Investigating dielectrics, volume currents, magnetic currents, ...



Slides: http://www.eit.lth.se/staff/mats.gustafsson

#### Antenna current optimization and physical bounds

- M. Gustafsson, M. Cismasu, B.L.G. Jonsson, *Physical bounds and optimal currents on antennas*, IEEE-TAP, 2012.
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- M. Cismasu, M. Gustafsson, Antenna Bandwidth Optimization with Single Frequency Simulation, IEEE-TAP, 2014.
- ▶ M. Gustafsson etal, Tutorial on antenna current optimization using MATLAB and CVX, 2015.

#### Stored energy expressed in the current density

- ▶ G.A.E. Vandenbosch, *Reactive energies, impedance, and Q factor of radiating structures,* IEEE-TAP, 2010.
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## Outline

#### **6** Physical bounds

Chu bound Forward scattering Polarizability dyadics

**7** Stored energy

**8** Current optimization

- ▶ 1947 Wheeler: Bounds based on circuit models.
- ▶ 1948 Chu: Bounds on Q and D/Q for spheres.
- 1964 Collin & Rothschild: Closed form expressions of Q for arbitrary spherical modes, see also Harrington, Collin, Fantes, Maclean, Gayi, Hansen, Hujanen, Sten, Best, Yaghjian, Kildal, Karlsson... (most are based on Chu's approach using spherical modes.)
- 1999 Foltz & McLean, 2001 Sten, Koivisto, and Hujanen: Initial bounds for spheroidal volumes.
- ▶ 2006 Thal: Bounds on Q for small non-magnetic spherical antennas.
- ▶ 2007 Gustafsson, Sohl & Kristensson: Bounds on D/Q for arbitrary geometries (and Q for small antennas).
- $\blacktriangleright$  2010 Yaghjian & Stuart: Bounds on Q for dipole antennas in the limit  $ka \rightarrow 0.$
- ▶ 2011 Vandenbosch: Bounds on Q for small (non-magnetic) antennas in the limit  $ka \rightarrow 0$ .
- ▶ 2011 Chalas, Sertel & Volakis: Bounds on Q using characteristic modes.
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- ▶ 2011 Chalas, Sertel & Volakis: Bounds on Q using characteristic modes.
- ▶ 2012 Gustafsson, Cismasu, & Jonsson: Optimal charge and current distributions on antennas.





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#### Chu 1948



The stored energy and radiated power outside a sphere with radius a give the Chu-bounds for omni-directional antennas, *i.e.*,

$$Q \ge Q_{\mathrm{Chu}} = rac{1}{(ka)^3} + rac{1}{ka} \quad \mathrm{and} \ rac{D}{Q} \le rac{3}{2Q_{\mathrm{Chu}}} pprox rac{3}{2} (ka)^3$$

for  $k_0 a \ll 1$ , where  $k = k_0$  is the resonance wavenumber  $k = 2\pi/\lambda = 2\pi f/c_0.$ 

#### Chu 1948



The stored energy and radiated power outside a sphere with radius a give the Chu-bounds for omni-directional antennas, *i.e.*,

$$Q \geq Q_{\mathrm{Chu}} = \frac{1}{(ka)^3} + \frac{1}{ka} \quad \text{and} \ \frac{D}{Q} \leq \frac{3}{2Q_{\mathrm{Chu}}} \approx \frac{3}{2} (ka)^3$$

for  $k_0a \ll 1$ , where  $k = k_0$  is the resonance wavenumber  $k = 2\pi/\lambda = 2\pi f/c_0$ . see also Sievenpiper et al. 2012

## Based on the approach of Chu 1948

Chu 1948 used mode expansions combined with circuit models to compute the stored energy. Fine for the dipole mode but technical for higher order modes. There have been a substantial amount of work following the approach by Chu, *e.g.*, (and many more...)

- Collin and Rothschild 1964: EM fields for closed form expressions of Q for arbitrary spherical modes.
- ► Fante 1969: general TE+TM modes.
- ▶ McLean 1996: a re-examination of Q.
- Foltz and McLean 1999; Sten, Koivisto, and Hujanen 2001: extensions to spheroidal volumes.
- Sten, Hujanen, and Koivisto 2001: antennas close to a ground plane.
- Geyi 2003b: Q and G/Q for combined TE+TM.
- Karlsson 2004: *lossy medium*.
- ▶ Thal 2006: bounds on Q for small hollow spherical antennas.
- Hansen, Kim, and Breinbjerg 2012: material core.
- Kim 2012: antennas that are close to the Chu limit.

## Thal 2006: non-magnetic spheres

The Chu bound is derived under the assumption of negligible stored energy in the interior of the sphere. Antennas without magnetic material (or magnetic currents) have internally stored energy.

Thal 2006: Bounds on Q for small non-magnetic spherical antennas. Small electric dipole antennas

$$Q \ge \frac{1.5}{(ka)^3} = 1.5 Q_{\text{Chu}} \quad \text{for } ka \ll 1$$

see also Gustafsson and Jonsson 2015b: Hansen and Collin 2009

Illustrations of surface currents J for a dipole, capped dipole, and folded spherical helix. Gustafsson, Cismasu, and Jonsson 2012







### Forward scattering bounds on antennas



- Properties of the best antenna confined to a given (arbitrary) geometry, e.g., spheroid, cylinder, elliptic disk, and rectangle.
- Performance in
  - Directivity bandwidth product: D/Q (half-power  $B \approx 2/Q$ ).
  - Partial realized gain:  $(1 |\Gamma|^2)G$  over a bandwidth.

Derneryd et al. 2009; Gustafsson, Sohl, and Kristensson 2007; Gustafsson, Sohl, and Kristensson 2009; Sohl and Gustafsson 2008

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## Forward scattering identity (2007)

The forward scattering identity (lossless, non-magnetic, linearly polarized  $(\hat{e})$  antennas)

$$\int_0^\infty \frac{(1-|\boldsymbol{\Gamma}(k)|^2)D(k;\hat{\boldsymbol{k}},\hat{\boldsymbol{e}})}{k^4} \, \mathrm{d}k = \frac{\eta}{2}\hat{\boldsymbol{e}}\cdot\boldsymbol{\gamma}_\mathrm{e}\cdot\hat{\boldsymbol{e}}$$

gives a bound on D/Q (directivity bandwidth product) expressed in the high contrast polarizability dyadic  $\gamma_{\infty} \geq \gamma_{\rm e}$ :

$$\frac{D}{Q} \leq \frac{\eta k_0^3}{2\pi} \hat{\boldsymbol{e}} \cdot \boldsymbol{\gamma}_\infty \cdot \hat{\boldsymbol{e}} \quad \text{and small E-dipoles } Q \geq \frac{6\pi}{k_0^3 \hat{\boldsymbol{e}} \cdot \boldsymbol{\gamma}_\infty \cdot \hat{\boldsymbol{e}}}$$

Circumscribing geometries of arbitrary shape. Performance proportional to the polarizability. **57** Identical to the Thal 2006 bound for spheres. Derneryd et al. 2009; Gustafsson, Sohl, and Kristensson 2007; Gustafsson, Sohl, and Kristensson 2009; Sohl and Gustafsson 2008; Sohl, Gustafsson, and Kristensson 2007





## Cylindrical dipole



Lossless  $\hat{z}$ -directed dipole, wire diameter  $d = \ell/1000$ , matched to  $72 \Omega$ . Weighted area under the black curve (partial realized gain) is known. Note, half wavelength dipole for  $ka = \pi/2 \approx 1.5$  with directivity  $D \approx 1.64 \approx 2.15 \,\mathrm{dB_i}$ .

## Circumscribing rectangles (2007)



## Circumscribing rectangles (2007)



## Small planar antennas



The dependence of  $Qk_0^3a^3$  as a function of  $\xi = \ell_1/\ell_2$ .

- ► Multiplication of Q with k<sub>0</sub><sup>3</sup>a<sup>3</sup> removes the dependence of the electrical size.
- ► A performance bound on  $Qk_0^3a^3$  (for  $k_0a \ll 1$ ) that only depends on the shape  $\xi = \ell_1/\ell_2$

Also explains the 'poor' performance of one of the antennas.
 Best 2009

### Circumscribing cylinders



## Polarizability dyadic and induced dipole moment

#### The induced dipole moment can be written

$$oldsymbol{p} = \epsilon_0 oldsymbol{\gamma}_{ ext{e}} \cdot oldsymbol{E}$$

where  $\gamma_{\mathrm{e}}$  is the polarizability dyadic.

#### Example (Dielectric sphere)

A dielectric sphere with radius a and relative permittivity  $\epsilon_{\rm r}$  has the polarizability dyadic

$$\boldsymbol{\gamma}_{\mathrm{e}} = 4\pi a^{3} \frac{\epsilon_{\mathrm{r}} - 1}{\epsilon_{\mathrm{r}} + 2} \mathbf{I} \rightarrow \boldsymbol{\gamma}_{\infty} = 4\pi a^{3} \mathbf{I}$$

as  $\epsilon_{\mathrm{r}} 
ightarrow \infty$ .

Analytic expressions for spheroids, elliptic discs, half spheres, hollow half spheres, touching spheres,...



## High-contrast polarizability dyadics: $\gamma_\infty$

 $\gamma_\infty$  is determined from the induced normalized surface charge density,  $\rho,$  as

$$\hat{\boldsymbol{e}} \cdot \boldsymbol{\gamma}_{\infty} \cdot \hat{\boldsymbol{e}} = \frac{1}{E_0} \int_{\Omega} \hat{\boldsymbol{e}} \cdot \boldsymbol{r} \rho(\boldsymbol{r}) \, \mathrm{dS}$$

where  $\rho$  satisfies the integral equation

$$\int_{\Omega} \frac{\rho(\boldsymbol{r}')}{4\pi |\boldsymbol{r} - \boldsymbol{r}'|} \, \mathrm{dS}' = E_0 \boldsymbol{r} \cdot \hat{\boldsymbol{e}} - V_n$$

with the constraints of zero total charge

$$\int_{\varOmega_n} \rho(\boldsymbol{r}) \, \mathrm{dS} = 0$$

Can also use FEM (Laplace equation).







#### External electrostatic field along the dipoles





## Properties of the polarizability dyadics

Removal of metal from circular and square plates



- The polarizability can not increase if you remove material.
- The metal in the center of the structure does not contribute much to the polarizability.
- Volume (and large area) is not necessary for a large polarizability.
- Important to be able to support a large separation of charge.
## Numerical evaluation of $\gamma_\infty$ (single object)

Expand the charge density in basis functions

$$\rho(\boldsymbol{r}) = \sum_{n=1}^{N} \rho_n \psi_n(\boldsymbol{r}) = \boldsymbol{\psi}^{\mathsf{T}} \boldsymbol{\rho}$$

and solve using Galerkin's method:

$$\begin{cases} \mathbf{W}_{e}^{(0)}\boldsymbol{\rho} = E_{0}\mathbf{f}_{e} - \mathbf{n}V & \\ \mathbf{f}_{e}^{\mathsf{T}}\boldsymbol{\rho} = E_{0}/\gamma & \\ \mathbf{n}^{\mathsf{T}}\boldsymbol{\rho} = 0 & \\ \end{cases} \begin{pmatrix} \mathbf{W}_{e}^{(0)} & \mathbf{f}_{e} & \mathbf{n} \\ \mathbf{f}_{e}^{\mathsf{T}} & 0 & 0 \\ \mathbf{n}^{\mathsf{H}} & 0 & 0 \end{pmatrix} \begin{pmatrix} \boldsymbol{\rho} \\ \gamma^{-1} \\ V \end{pmatrix} = \begin{pmatrix} \mathbf{0} \\ -1 \\ 0 \end{pmatrix}$$

where  $E_0 = -\gamma$  and ( $N \times 1$  matrices)

$$\mathbf{f}_{e} = \int_{\Omega} (\hat{\boldsymbol{e}} \cdot \boldsymbol{r}) \boldsymbol{\psi}(\boldsymbol{r}) \, dS, \quad \mathbf{n} = \int_{\Omega} \boldsymbol{\psi}(\boldsymbol{r}) \, dS$$

and the  $N\times N$  matrix

$$\mathbf{W}_{\mathrm{e}}^{(0)} = \int_{\Omega} \int_{\Omega} \frac{\psi(\boldsymbol{r})\psi^{\mathsf{T}}(\boldsymbol{r}')}{4\pi |\boldsymbol{r} - \boldsymbol{r}'|} \,\mathrm{dSdS'}.$$









Constant charge (p = 2)

## Rectangles, cylinders, elliptic disks, and spheroids (2007)



# Bounds on D/Q (and Q for small antennas)

- Forward scattering (2007).
- Performance in the polarizability.
- Numerical simulations verify the results for electric dipole antennas.
- Similar results for small electric dipole antennas by Yaghjian & Stuart (2010), Vandenbosch (2011), Chalas, Sertel & Volakis (2011), and Gustafsson *etal*(2012).
- Many open questions for mixed modes (TE+TM) and magnetic materials.

#### What more can we do?

#### Antenna current optimization for

- embedded antennas (mobile phones).
- superdirectivity, efficiency, MIMO...
- current distribution for understanding.



# Outline

### **6** Physical bounds

Chu bound Forward scattering Polarizability dyadics

#### Stored energy

#### **8** Current optimization

## Subtracted far field: negative $W_{\rm e}$

The stored energy defined by subtraction of the far field

$$W_{\mathrm{F}}^{(\mathrm{E})} = \frac{\epsilon_0}{4} \int_{\mathbb{R}^3_r} |\boldsymbol{E}(\boldsymbol{r})|^2 - \frac{|\boldsymbol{F}(\hat{\boldsymbol{r}})|^2}{r^2} \,\mathrm{d} \mathbf{V}$$

can produce negative values. Coordinate independent for symmetric radiation patterns and equals the energy expression in Vandenbosch 2010, see Gustafsson and Jonsson 2015b.

- ► Consider *e.g.*, the divergence free loop current  $J(\mathbf{r}) = I_0 \delta(\varrho a) \delta(z) \hat{\boldsymbol{\phi}}$  in cylinder coordinates  $\{\varrho, \phi, z\}$ .
- Stored electric energy ( $W_{
  m F}^{
  m (M)}=\infty$ )

$$W_{\rm F}^{\rm (E)} = \frac{-\mu_0 k a^3 I_0^2}{16} \int_0^{2\pi} \sin \phi \sin(2ka \sin \frac{\phi}{2}) \, {\rm d}\phi$$



► Can produce negative values for lager structures. Gustafsson, Cismasu, Jonsson, Physical Bounds and Optimal Currents on Antennas, IEEE-TAP 2012.

Consider a voltage source and use the Kirchoffs' laws to construct the linear system  $\mathbf{ZI} = \mathbf{V}$ , where the impedance matrix  $\mathbf{Z} = \mathbf{R} + j\mathbf{X}$  contains elements of the form

$$Z_{ij} = R_{ij} + jX_{ij} = R_{ij} + j\left(\omega L_{ij} - \frac{1}{\omega C_{ij}}\right)$$

The differentiated impedance matrix  $\mathbf{Z}'=j\mathbf{X}'$  is imaginary valued with the elements

$$X'_{ij} = \frac{\partial}{\partial \omega} \left( \omega L_{ij} - \frac{1}{\omega C_{ij}} \right) = L_{ij} + \frac{1}{\omega^2 C_{ij}}.$$

Differentiated input admittance and impedance

$$Y_{
m in}'=-{
m j}{f I}^{
m T}{f X'}{f I}/V_{
m in}^2$$
 and  $Z_{
m in}'=-Z_{
m in}^2Y_{
m in}'={
m j}{f I}^{
m T}{f X'}{f I}/I_{
m in}^2$ 

## Energy in lumped circuits



Time average stored energy in capacitors and in inductors

$$W_{\rm e}=\frac{C|V|^2}{4}=\frac{|I|^2}{4\omega^2 C}\quad {\rm and}\ W_{\rm m}=\frac{L|I|^2}{4}$$

Contain absolute values  $|I|^2$  and  $|V|^2$ , need to use Hermitian transpose. For a circuit network

$$W_{\mathrm{m}} - W_{\mathrm{e}} = rac{\mathbf{I}^{\mathsf{H}} \mathbf{X} \mathbf{I}}{4\omega} \quad \text{and} \ W_{\mathrm{e}} + W_{\mathrm{m}} = rac{\mathbf{I}^{\mathsf{H}} \mathbf{X}' \mathbf{I}}{4} \geq 0$$

reactance  ${\bf X}$  for difference  $W_{\rm m}-W_{\rm e}$  and differentiated reactance  ${\bf X}'$  the sum  $W_{\rm m}+W_{\rm e}.$ 

## Energy in lumped circuits



Time average stored energy in capacitors and in inductors

$$W_{\rm e} = rac{C|V|^2}{4} = rac{|I|^2}{4\omega^2 C} \quad {\rm and} \ W_{\rm m} = rac{L|I|^2}{4}$$

Contain absolute values  $|I|^2$  and  $|V|^2,$  need to use Hermitian transpose. For a circuit network

$$W_{\rm m} = \frac{1}{8} \mathbf{I}^{\mathsf{H}} \left( \frac{\partial \mathbf{X}}{\partial \omega} + \frac{\mathbf{X}}{\omega} \right) \mathbf{I} = \frac{1}{4} \sum_{i,j=1}^{N} I_i^* L_{ij} I_j \ge 0$$
$$W_{\rm e} = \frac{1}{8} \mathbf{I}^{\mathsf{H}} \left( \frac{\partial \mathbf{X}}{\partial \omega} - \frac{\mathbf{X}}{\omega} \right) \mathbf{I} = \frac{1}{4\omega^2} \sum_{i,j=1}^{N} I_i^* C_{ij}^{-1} I_j \ge 0,$$

## Q and $Q_{\mathrm{Z}'}$ for lumped circuits

Assume for simplicity a self-resonant circuit (antenna)

$$Q_{\mathbf{Z}'} = \frac{\omega |Z'_{\text{in}}|}{2R_{\text{in}}} = \frac{\omega |\mathbf{I}^{\mathrm{T}} \mathbf{X}' \mathbf{I}|}{2\mathbf{I}^{\mathsf{H}} \mathbf{R} \mathbf{I}}$$

and

$$Q = \frac{2\omega \max\{W_{\rm e}, W_{\rm m}\}}{P_{\rm d}} = \frac{\omega \mathbf{I}^{\rm H} \mathbf{X}' \mathbf{I}}{2\mathbf{I}^{\rm H} \mathbf{R} \mathbf{I}}$$

Transpose for  $Q_{Z'}$  and Hermitian transpose for Q

Also the inequality  $Q \ge Q_{Z'}$  as  $(\mathbf{X}' = \mathbf{U}^{\mathrm{T}} \mathbf{\Lambda} \mathbf{U}$  real valued)

$$\mathbf{I}^{\mathsf{H}}\mathbf{X}'\mathbf{I} = (\mathbf{U}\mathbf{I})^{\mathsf{H}}\mathbf{\Lambda}\mathbf{U}\mathbf{I} \geq \left|(\mathbf{U}\mathbf{I})^{\mathrm{T}}\mathbf{\Lambda}\mathbf{U}\mathbf{I}\right| = \left|\mathbf{I}^{\mathrm{T}}\mathbf{X}'\mathbf{I}\right| \geq 0$$

with equality (to 0) for some current I (in the matrix case).

## Electrostatic stored energy

- Consider the charge density ρ(r) supported in Ω ⊂ ℝ<sup>3</sup> in free space. Also assume that the total charge is zero, ∫ ρ dV = 0.
- Have the alternative electric energy expressions

$$\begin{split} W_{\mathrm{e}} &= \frac{1}{2} \int_{\mathbb{R}^3} \epsilon_0 |\boldsymbol{E}(\boldsymbol{r})|^2 \, \mathrm{dV} = \frac{1}{2} \int_{\Omega} \phi(\boldsymbol{r}) \rho(\boldsymbol{r}) \, \mathrm{dV} \\ &= \frac{1}{2\epsilon_0} \int_{\Omega} \int_{\Omega} \frac{\rho(\boldsymbol{r}_1) \rho(\boldsymbol{r}_2)}{4\pi |\boldsymbol{r}_1 - \boldsymbol{r}_2|} \, \mathrm{dV}_1 \, \mathrm{dV}_2 \end{split}$$

where  $\phi$  is the potential and  $\rho$  the charge density.

- Alternative interpretations: Energy in the fields or energy in the charges.
- Alternative computation: integral over  $\mathbb{R}^3$  or over  $\Omega$ .
- Positive definite quadratic form suitable for optimization.

## Stored EM energy from current densities $\boldsymbol{J}$ in V

We use the expressions by Vandenbosch 2010 (and Carpenter 1989, Geyi 2003b for small antennas). Stored electric energy

$$W_{\rm e} = \frac{\eta_0}{4\omega} \int_{\Omega} \int_{\Omega} \nabla_1 \cdot \boldsymbol{J}(\boldsymbol{r}_1) \nabla_2 \cdot \boldsymbol{J}^*(\boldsymbol{r}_2) \frac{\cos(kr_{12})}{4\pi k r_{12}} \,\mathrm{dV}_1 \,\mathrm{dV}_2 + W^{(2)}$$

#### Stored magnetic energy

$$W_{\rm m} = \frac{\eta_0}{4\omega} \int_{\Omega} \int_{\Omega} k^2 \boldsymbol{J}(\boldsymbol{r}_1) \cdot \boldsymbol{J}^*(\boldsymbol{r}_2) \frac{\cos(kr_{12})}{4\pi kr_{12}} \,\mathrm{dV}_1 \,\mathrm{dV}_2 + W^{(2)}$$

where 
$$j\omega\rho = -\nabla\cdot \boldsymbol{J}$$
,  $\phi = \epsilon_0^{-1}g*\rho$ ,  $\boldsymbol{A} = \mu_0g*\boldsymbol{J}$ ,  $r_{12} = |\boldsymbol{r}_1 - \boldsymbol{r}_2|$ 

$$W^{(2)} = \frac{\eta_0}{8\omega} \int_{\Omega} \int_{\Omega} \left( \nabla_1 \cdot \boldsymbol{J}_1 \nabla_2 \cdot \boldsymbol{J}_2^* - k^2 \boldsymbol{J}_1 \cdot \boldsymbol{J}_2^* \right) \frac{\sin(kr_{12})}{4\pi} \, \mathrm{dV}_1 \, \mathrm{dV}_2$$

## Stored EM energy from current densities $\boldsymbol{J}$ in V

We use the expressions by Vandenbosch 2010 (and Carpenter 1989, Geyi 2003b for small antennas). Stored electric energy

$$W_{\rm e} = \frac{1}{4\epsilon_0} \operatorname{Re} \int_{\Omega} \int_{\Omega} \rho(\boldsymbol{r}_1) \rho^*(\boldsymbol{r}_2) \frac{\mathrm{e}^{-\mathrm{j}kr_{12}}}{4\pi r_{12}} \,\mathrm{dV}_1 \,\mathrm{dV}_2 + W^{(2)}$$

Stored magnetic energy

$$W_{\rm m} = \frac{\mu_0}{4} \operatorname{Re} \int_{\Omega} \int_{\Omega} \boldsymbol{J}(\boldsymbol{r}_1) \cdot \boldsymbol{J}^*(\boldsymbol{r}_2) \frac{\mathrm{e}^{-\mathrm{j}kr_{12}}}{4\pi r_{12}} \,\mathrm{dV}_1 \,\mathrm{dV}_2 + W^{(2)}$$

where 
$$j\omega\rho = -\nabla \cdot \boldsymbol{J}$$
,  $\phi = \epsilon_0^{-1}g * \rho$ ,  $\boldsymbol{A} = \mu_0 g * \boldsymbol{J}$ ,  $r_{12} = |\boldsymbol{r}_1 - \boldsymbol{r}_2|$ 

$$W^{(2)} = \frac{\eta_0}{8\omega} \int_{\Omega} \int_{\Omega} \left( \nabla_1 \cdot \boldsymbol{J}_1 \nabla_2 \cdot \boldsymbol{J}_2^* - k^2 \boldsymbol{J}_1 \cdot \boldsymbol{J}_2^* \right) \frac{\sin(kr_{12})}{4\pi} \,\mathrm{dV}_1 \,\mathrm{dV}_2$$

## Stored EM energy from current densities $\boldsymbol{J}$ in V

We use the expressions by Vandenbosch 2010 (and Carpenter 1989, Geyi 2003b for small antennas). Stored electric energy

$$W_{\rm e} = \frac{1}{4} \operatorname{Re} \int_{\Omega} \phi(\boldsymbol{r}) \rho^*(\boldsymbol{r}) \, \mathrm{dV} + W^{(2)}$$

Stored magnetic energy

$$W_{\rm m} = \frac{1}{4} \operatorname{Re} \int_{\Omega} \boldsymbol{A}(\boldsymbol{r}) \cdot \boldsymbol{J}^*(\boldsymbol{r}) \, \mathrm{dV} + W^{(2)}$$

where  $j\omega\rho = -\nabla \cdot \boldsymbol{J}$ ,  $\phi = \epsilon_0^{-1}g * \rho$ ,  $\boldsymbol{A} = \mu_0 g * \boldsymbol{J}$ ,  $r_{12} = |\boldsymbol{r}_1 - \boldsymbol{r}_2|$ 

$$W^{(2)} = \frac{\eta_0}{8\omega} \int_{\Omega} \int_{\Omega} \left( \nabla_1 \cdot \boldsymbol{J}_1 \nabla_2 \cdot \boldsymbol{J}_2^* - k^2 \boldsymbol{J}_1 \cdot \boldsymbol{J}_2^* \right) \frac{\sin(kr_{12})}{4\pi} \,\mathrm{dV}_1 \,\mathrm{dV}_2$$

### Bandwidth



### Bandwidth



### Bandwidth



## Dispersive media

The frequency derivative of the EFIE impedance matrix  ${f Z}$  is

$$\omega \frac{\partial Z_{ij}}{\partial \omega} = k \frac{\partial (Z_{ij}/\eta)}{\partial k} \frac{\eta \omega}{k} \frac{\partial k}{\partial \omega} + \omega \frac{Z_{ij}}{\eta} \frac{\partial \eta}{\partial \omega}$$

for a temporally dispersive background medium with  $k=\omega\sqrt{\epsilon\mu}$  and  $\eta=\sqrt{\mu/\epsilon}.$  The derivative simplifies to

$$\omega \frac{\partial Z_{ij}}{\partial \omega} = k \frac{\partial (Z_{ij}/\eta)}{\partial k} \eta \left( \frac{\omega \partial \epsilon}{2\epsilon \partial \omega} + 1 \right) - \frac{Z_{ij}}{2} \frac{\omega \partial \epsilon}{\epsilon \partial \omega}$$

for the common case of a non-magnetic medium,  $\mu_{\rm r}=1.$ 

Multiplication of the previously calculated derivative (with respect to the wavenumber k in the medium) with a factor that only depends on the medium. The factor  $\omega \epsilon' = (\omega \epsilon)' - \epsilon$  is similar to the classical approach used to define the energy density in dispersive media.

#### Numerical examples: Debye media



#### Numerical examples: Debye media



#### Numerical examples: Debye media



#### Numerical examples: Lorentz media



#### Numerical examples: Lorentz media



### Numerical examples: Lorentz $\epsilon_{\rm r} = \mu_{\rm r}$ media



### Numerical examples: Lorentz $\epsilon_{\rm r} = \mu_{\rm r}$ media



## Brune synthesis

Iterative procedure to synthesize circuit models from PR (positive real rational functions) by Brune 1931.

- Approximate the input impedance with a rational PR function (hard problem).
- 2. Apply Brune synthesis and compute the stored energy in the capacitors and inductors.



# Outline

#### **6** Physical bounds

- Chu bound Forward scattering Polarizability dyadics
- **7** Stored energy

#### **(B)** Current optimization





 $(Q_{\rm e} + Q_{\rm m})/2$   $(Q_{\rm e} - Q_{\rm m})/2$   $Q_{\rm e}$  $Q_{\rm m}$ 



 $(Q_{\rm e} + Q_{\rm m})/2$   $(Q_{\rm e} - Q_{\rm m})/2$   $Q_{\rm e}$  $Q_{\rm m}$ 



$$(Q_{\rm e} + Q_{\rm m})/2$$
  $(Q_{\rm e} - Q_{\rm m})/2$   $Q_{\rm e}$   $Q_{\rm m}$ 



$$(Q_{\rm e} + Q_{\rm m})/2$$
  $(Q_{\rm e} - Q_{\rm m})/2$   $Q_{\rm e}$   $Q_{\rm m}$ 



## ${\rm Minimization} \ {\rm of} \ Q$

Compare maximization of G/Q with minimization of Q. Use the same inequality for  $0 \leq \alpha \leq 1$ 

$$Q = \frac{\max\{\mathbf{I}^{\mathsf{H}} \mathbf{X}_{e} \mathbf{I}, \mathbf{I}^{\mathsf{H}} \mathbf{X}_{m} \mathbf{I}\}}{\mathbf{I}^{\mathsf{H}} \mathbf{R}_{r} \mathbf{I}} = \max\{Q_{e}, Q_{m}\}$$
$$\geq \alpha Q_{e} + (1 - \alpha) Q_{m} = \frac{\mathbf{I}^{\mathsf{H}} (\alpha \mathbf{X}_{e} + (1 - \alpha) \mathbf{X}_{m}) \mathbf{I}}{\mathbf{I}^{\mathsf{H}} \mathbf{R}_{r} \mathbf{I}}$$

The lower bound on Q,  $Q_{\rm lb}$ , is a minimization problem for a Rayleigh quotient solved as a generalized eigenvalue problem

$$\min \operatorname{eig}(\alpha \mathbf{X}_e + (1-\alpha) \mathbf{X}_m, \mathbf{R}_r)$$

Let  $Q_{\rm e\alpha}$  and  $Q_{\rm m\alpha}$  denote the corresponding electric and magnetic Q-factors to get the estimate

$$\alpha Q_{\mathrm{e}\alpha} + (1 - \alpha) Q_{\mathrm{m}\alpha} \le Q_{\mathrm{lb}} \le \max\{Q_{\mathrm{e}\alpha}, Q_{\mathrm{m}\alpha}\}$$

for the lower bound  $Q_{\rm lb}$ .

# Numerical illustration of $\min .Q$ and $\max .G/Q$

- ► The formulation for min.Q has a duality gap, *i.e.*, we have an interval for Q<sub>lb</sub> here 88 ≤ Q<sub>lb</sub> ≤ 106.
- ► The optimization problem min.Q is not convex.
- The formulation for max.G/Q has no duality gap.
- This is common for many convex optimization problems.

